## Amendments to the Abstract:

## Abstract of the Disclosure

In the-cleaning using the-a self-propelled cleaning device, firstly the cleaning device moves alongside the-a wall surface and then a reference direction is set.

Next, the cleaning device advances alongside the wall surface by at a prescribed distance, makes a right-angle turn, and travels in the reference direction. When the cleaning device reaches the surface of the-an opposing wall, it moves in a spiraling manner. At that time, the orientation angle of the cleaning device, which is estimated using a gyro sensor, is checked and corrected. If an obstacle is encountered while traveling, the cleaning device travels on a path that avoids the obstacle or travels in a spiral manner in a region in front of the obstacle.